

1. Symmetry of the 2nd Differential

Theorem:

Pre.: Let $n \in \mathbb{N}_+$.

Let G be an open subset of \mathbb{R}^n .

Let $\varphi : G \rightarrow \mathbb{R}$ be a mapping.

Let φ be twice differentiable.

Ass.: $\forall p \in G \quad d_p^2 \varphi : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$ is symmetric

2. A Special Case of Cartan's Derivation

Theorem:

Pre.: Let $n \in \mathbb{N}_+$.

Let G be an open subset of \mathbb{R}^n .

Let $V : G \rightarrow \mathbb{R}^n$ be a continuous differentiable mapping.

Let $\omega : G \rightarrow \mathfrak{L}(\mathbb{R}^n, \mathbb{R})$ be defined as $\omega := \sum_{i=1}^n V_i \cdot dx_i$

(especially $\omega : G \rightarrow \mathfrak{L}(\mathbb{R}^n, \mathbb{R})$ is continuous differentiable).

Ass.: $\forall p \in G \quad \left(\mathfrak{D}_p \omega = 0 \quad \Leftrightarrow \quad d_p V \text{ ist self-adjoint} \right)$

Rem.: 1. $\mathfrak{L}(\mathbb{R}^n, \mathbb{R})$ is the \mathbb{R} -vector-space of all \mathbb{R} -linear-forms $\mathbb{R}^n \rightarrow \mathbb{R}$.

2. ω is a so called C^1 -differential form of degree 1.

3. $\mathfrak{D} \dots$ is Cartan's derivation. If $n = 3$, then the following is true:

$$\forall p \in G \quad \left(\left(\mathfrak{D}_p \omega = 0 \right) \quad \Leftrightarrow \quad \left(\text{curl}_p (V) = 0 \right) \right).$$

3. Vector Potential

Theo.:

Pre.: Let $n \in \mathbb{N}_+$.

Let G be an open subset of \mathbb{R}^n .

Ass.: 1. Let $\varphi \in C^2(G)$.

Then the following is true:

$$\left(\forall p \in G \quad (d_p(\text{grad}(\varphi)) \text{ ist self-adjoint}) \right)$$

2. Be G star-shaped.

Be $k \in \mathbb{N}_+ \cup \{\infty\}$.

Let $V : G \rightarrow \mathbb{R}^n$ be a k -times continuous differentiable mapping.

Then the following is true:

$$\left(\forall p \in G \quad (d_p V \text{ ist self-adjoint}) \right) \Rightarrow$$

$$\exists \varphi \in C^{k+1}(G) \quad V = \text{grad}(\varphi)$$

4. The Inversal of 1

Theorem:

Pre.: Let $n \in \mathbb{N}_+$.

Let G be an open, star-shaped subset of \mathbb{R}^n .

Let $\alpha : G \rightarrow \mathfrak{L}(\mathbb{R}^n, \mathbb{R})$ be a continuous differentiable mapping.

Let $\beta : G \rightarrow \mathfrak{L}^2(\mathbb{R}^n, \mathbb{R})$ be defined through

$$\forall p \in G \quad \forall v, w \in \mathbb{R}^n \quad (\beta_p)(v, w) := \left((d_p \alpha)(v) \right)(w)$$

Ass.: $\left(\forall p \in G \quad (\beta_p \text{ ist symmetric}) \right) \Rightarrow$
 $\left(\text{There is } \varphi \in C^2(G) \text{ with} \right)$
 $\left(d\varphi = \alpha \text{ and } d^2\varphi = \beta \right)$

Rem.: $\mathfrak{L}^2(\mathbb{R}^n, \mathbb{R}) = \{ b : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R} \text{ is bilinear} \}$ is a \mathbb{R} -vector-space.

Proof: Let $\mathfrak{E} := (e_1, \dots, e_n)$ be the standard base of \mathbb{R}^n .

Let $\mathfrak{X} := (x_1, \dots, x_n)$ be the base of $\mathfrak{L}(\mathbb{R}^n, \mathbb{R})$ dual to \mathfrak{E} .

Let the mapping $V : G \rightarrow \mathbb{R}^n$ be defined as

$$\forall p \in G \quad V(p) := \begin{pmatrix} \alpha_p(e_1) \\ \vdots \\ \alpha_p(e_n) \end{pmatrix} \quad (1)$$

Then the following statements are valid:

$$V : G \rightarrow \mathbb{R}^n \text{ is continuous differentiable} \quad (2)$$

and

$$\forall p \in G \quad d_p V = \begin{pmatrix} d_p(\alpha \dots (e_1)) \\ \vdots \\ d_p(\alpha \dots (e_n)) \end{pmatrix} = \begin{pmatrix} (d_p \alpha)(e_1) \\ \vdots \\ (d_p \alpha)(e_n) \end{pmatrix} \quad (3)$$

Then the following statement is true:

$$\forall j \in \{1, \dots, n\} \quad \forall p \in G \quad \left(d_p V \right) (e_j) = \frac{\partial V}{\partial x_j} \quad (4)$$

A consequence of (3) is

$$\forall j \in \{1, \dots, n\} \quad \forall p \in G \quad \left(d_p V \right) (e_j) = \begin{pmatrix} \left(d_p \alpha \right) (e_1) \\ \vdots \\ \left(d_p \alpha \right) (e_n) \end{pmatrix} (e_j)$$

Then it follows by premise:

$$\forall j \in \{1, \dots, n\} \quad \forall p \in G \quad \left(d_p V \right) (e_j) = \begin{pmatrix} \left(\beta_p \right) (e_1, e_j) \\ \vdots \\ \left(\beta_p \right) (e_n, e_j) \end{pmatrix} \quad (5)$$

Because $\left(\forall p \in G \quad \left(\beta_p \text{ ist symmetric} \right) \right)$, a consequence of (4) and (5) is

$$\left(\forall p \in G \quad \left(d_p V \text{ ist self-adjoint} \right) \right) \quad (6)$$

Because of (2), (6) and theorem 3.2., there exists $\varphi \in C^2(G)$ with

$$V = \text{grad}(\varphi) \quad (7)$$

Because of (1) and (7), for all $\forall i \in \{1, \dots, n\}$ and all $\forall p \in G$ the following statement is valid:

$$\left(d_p \varphi \right) (e_i) = \frac{\partial \varphi}{\partial x_i} (p) = \left(\text{grad}_p (\varphi) \right)_i = v_i (p) = \alpha_p (e_i)$$

respectively

$$d\varphi = \alpha \quad (8)$$

Then it follows for all $\forall i, j \in \{1, \dots, n\}$ and all $\forall p \in G$

$$d_p^2 \varphi(e_i, e_j) = (d_p ((d \dots \varphi)(e_i)))(e_j) = (d_p ((\alpha \dots)(e_i)))(e_j)$$

respectively

$$d_p^2 \varphi(e_i, e_j) = ((d_p (\alpha))(e_i))(e_j)$$

respectively by premise

$$d_p^2 \varphi(e_i, e_j) = (\beta_p(e_i, e_j))$$

At last we have

$$d^2 \varphi = \beta \tag{9}$$